

LINEAR ALGEBRA
EXAM 3
FALL 2021

Name: *Julian*

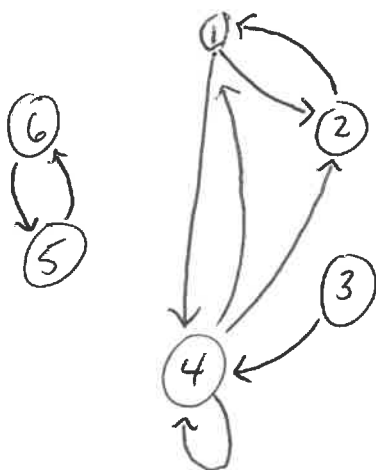
Honor Code Statement: *I have neither given nor received unauthorized aid on this exam.*

Signature: *C.F. Burns*

Directions: Complete all problems. Justify all answers/solutions; answers without justifying calculations will not receive credit. Calculators, cell-phones, texts, and notes are not permitted – the only permitted items to use are pens, pencils, rulers and erasers. Good luck!

- (1) [8 points] The following question is based upon the reading of *The 25 billion dollar eigenvector*. Consider the following link matrix, which is a column-stochastic matrix. Draw the corresponding web. Without doing any calculations, is there a page that will be ranked highest?

$$A = \begin{bmatrix} 0 & 1/2 & 0 & 1/3 & 0 & 0 \\ 1/2 & 0 & 0 & 1/3 & 0 & 0 \\ 0 & 1/2 & 0 & 0 & 0 & 0 \\ 1/2 & 0 & 1 & 1/3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$



Here's the web.

Perhaps a little strange that page 4 voted/linked for to itself.

As the web is not connected the dimension of the eigenspace is greater than 1. Thus, there is not a unique ranking. So no page is ranked highest.

70 points total
55 point avg.
15 point S.D.

(2) Let

$$A = \begin{bmatrix} -2 & -4 & 2 \\ -2 & 1 & 2 \\ 4 & 2 & 5 \end{bmatrix}$$

(a) [5 points] Show that 3 is an eigenvalue of A by finding the characteristic equation of A and evaluating at 3.

The characteristic equation is given by $\det(A - \lambda I) = 0$.

$$\text{So, } \det \begin{bmatrix} -2-\lambda & -4 & 2 \\ -2 & 1-\lambda & 2 \\ 4 & 2 & 5-\lambda \end{bmatrix} = 0. \text{ If } \lambda = 3, \text{ we get}$$

$$\begin{aligned} \det \begin{bmatrix} -5 & -4 & 2 \\ -2 & -2 & 2 \\ 4 & 2 & 2 \end{bmatrix} &= -5(-4+4) + 4(-4-8) + 2(-4+8) \\ &= 40 - 48 + 8 = 0 \end{aligned}$$

Thus, $\lambda = 3$ is an eigenvalue.

(b) [5 points] Show that 3 is an eigenvalue of A by performing Gaussian elimination on the correct augmented matrix.

We're interested in $A\vec{x} = 3\vec{x}$ or non-trivial solutions to $[A - 3I | \vec{0}]$. So, perform G.E. on

$$\begin{aligned} \left[\begin{array}{ccc|c} -5 & -4 & 2 & 0 \\ -2 & -2 & 2 & 0 \\ 4 & 2 & 2 & 0 \end{array} \right] &\sim \left[\begin{array}{ccc|c} 1 & 4/5 & -2/5 & 0 \\ 1 & 1 & -1 & 0 \\ 1 & 1/2 & 1/2 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 4/5 & -2/5 & 0 \\ 0 & 1/5 & -3/5 & 0 \\ 0 & -3/10 & 9/10 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 4/5 & -2/5 & 0 \\ 0 & 1/5 & -3/5 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \\ &\quad \begin{array}{l} -\frac{1}{5}R_1 \\ -\frac{1}{2}R_2 \\ +\frac{1}{4}R_3 \end{array} \qquad \begin{array}{l} -R_1 + R_2 \\ -R_1 + R_3 \end{array} \qquad \begin{array}{l} +\frac{3}{2}R_2 + R_3 \end{array} \end{aligned}$$

So we see that x_3 is free variable and the system is consistent. So, \exists a non-trivial solution, i.e. $\lambda = 3$ is an eigenvalue.

(c) [3 points] Give a basis for the eigenspace associated with $\lambda = 3$.

Continuing w/ row reduction ($-4R_2 + R_1$)

$$\sim \left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 0 & 1/5 & -3/5 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\begin{aligned} \text{So, } x_1 &= -2x_3 \\ \frac{1}{5}x_2 &= +\frac{3}{5}x_3 \Rightarrow x_2 = 3x_3 \\ x_3 &\text{ is free} \end{aligned}$$

$$\text{So } \vec{x} = \begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix}$$

and this one vector serves as a basis.

- (d) [2 points] State the dimension of the eigenspace associated with $\lambda = 3$.

Since there is one vector in the basis,
the dimension is 1.

- (e) [3 points] State how A acts on this eigenspace.

This eigenspace is a line through the origin
in the direction of $\begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix}$. The matrix A
acts on this line via dilation of a factor of 3.

- (f) [4 points] The matrix A has two additional eigenvalues. These are -5
and 6 . Is the matrix A diagonalizable? Why or why not?

Yes, the Diagonalization Theorem guarantees
this, as does Theorem ~~6.7~~ of Chapter 5.
6 and 7

- (g) [7 points] As -5 is an eigenvalue, there is an eigenvector associated to $\lambda = -5$. Call such a vector \mathbf{v}_1 . Prove that \mathbf{v}_1 is NOT a scalar multiple of any vector found in the eigenspace associated with $\lambda = 3$.

Here is a nice proof that one student wrote:

"Suppose to the contrary that \vec{v}_1 is a scalar multiple of a vector found in the eigenspace associated with $\lambda = 3$.

Then we have $A\vec{v}_1 = 3\vec{v}_1$

Since \vec{v}_1 is an eigenvector associated to $\lambda = -5$, we have $A\vec{v}_1 = -5\vec{v}_1$.

So, by transitivity,

$$-5\vec{v}_1 = 3\vec{v}_1$$

Thus, $\vec{v}_1 = \vec{0}$. This is a contradiction since eigenvectors are non-zero vectors. "

* Finding the basis for the eigenspace of $\lambda = -5$ via Gaussian Elimination was a computationally burdensome way to go through legitimate approach

- (3) [4 points] Is there a vector in \mathbb{R}^3 with first two coordinates 3 and 4 with length less than 5? If yes, give such an example. If no, explain why not.

$$\text{Let } \vec{x} = \begin{bmatrix} 3 \\ 4 \\ t \end{bmatrix} \in \mathbb{R}^3.$$

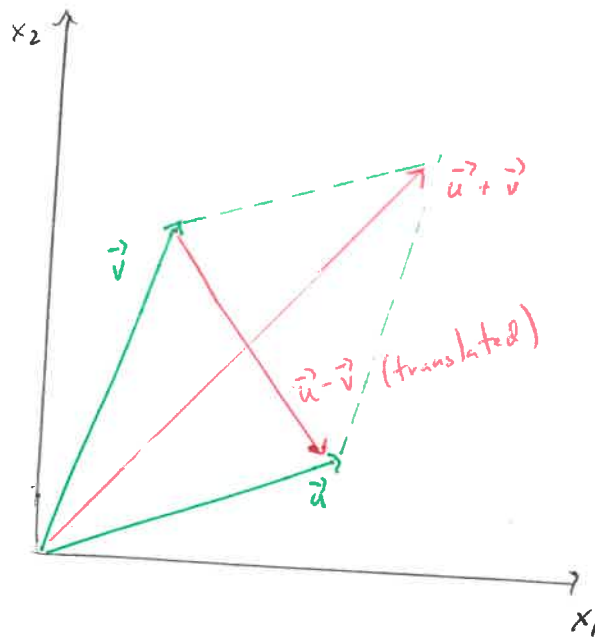
$$\text{Then } \|\vec{x}\| = \sqrt{3^2 + 4^2 + t^2} = \sqrt{25 + t^2}.$$

$$\text{However, } \sqrt{25 + t^2} \geq 5 \quad \forall t \in \mathbb{R}.$$

So, there is no such vector.

- (4) [6 points] Let \mathbf{u} and \mathbf{v} be two vectors in \mathbb{R}^2 , each with positive coordinates. Draw a picture that illustrates vectors involved in the following identity. Then use this figure to explain what the identity is saying.

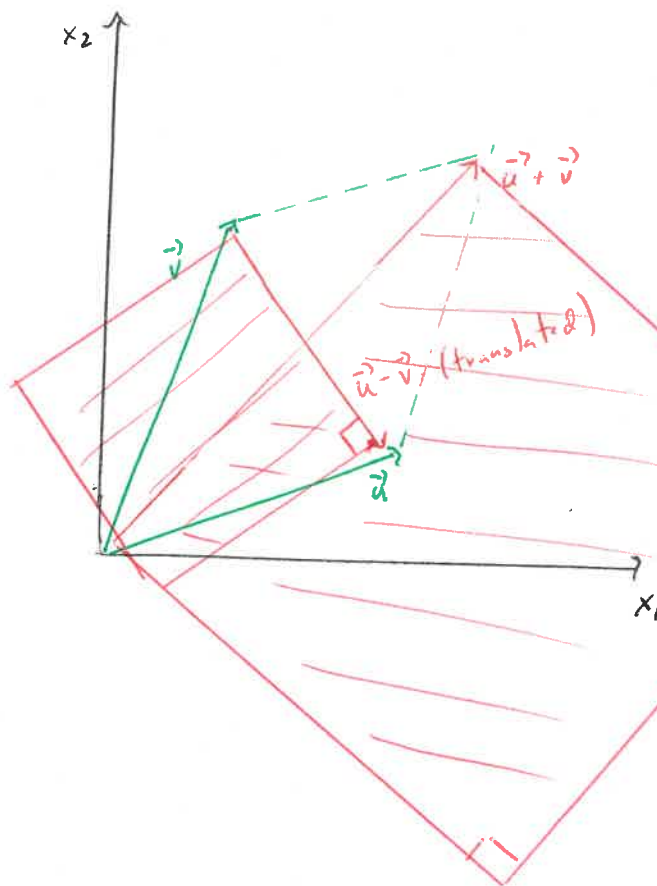
$$\|\mathbf{u} + \mathbf{v}\|^2 + \|\mathbf{u} - \mathbf{v}\|^2 = 2\|\mathbf{u}\|^2 + 2\|\mathbf{v}\|^2$$



The identity says that the sum of the squared lengths of the diagonals of a parallelogram is equal to the sum of the squared lengths of its sides.

- (4) [6 points] Let \mathbf{u} and \mathbf{v} be two vectors in \mathbb{R}^2 , each with positive coordinates. Draw a picture that illustrates vectors involved in the following identity. Then use this figure to explain what the identity is saying.

$$\|\mathbf{u} + \mathbf{v}\|^2 + \|\mathbf{u} - \mathbf{v}\|^2 = 2\|\mathbf{u}\|^2 + 2\|\mathbf{v}\|^2$$

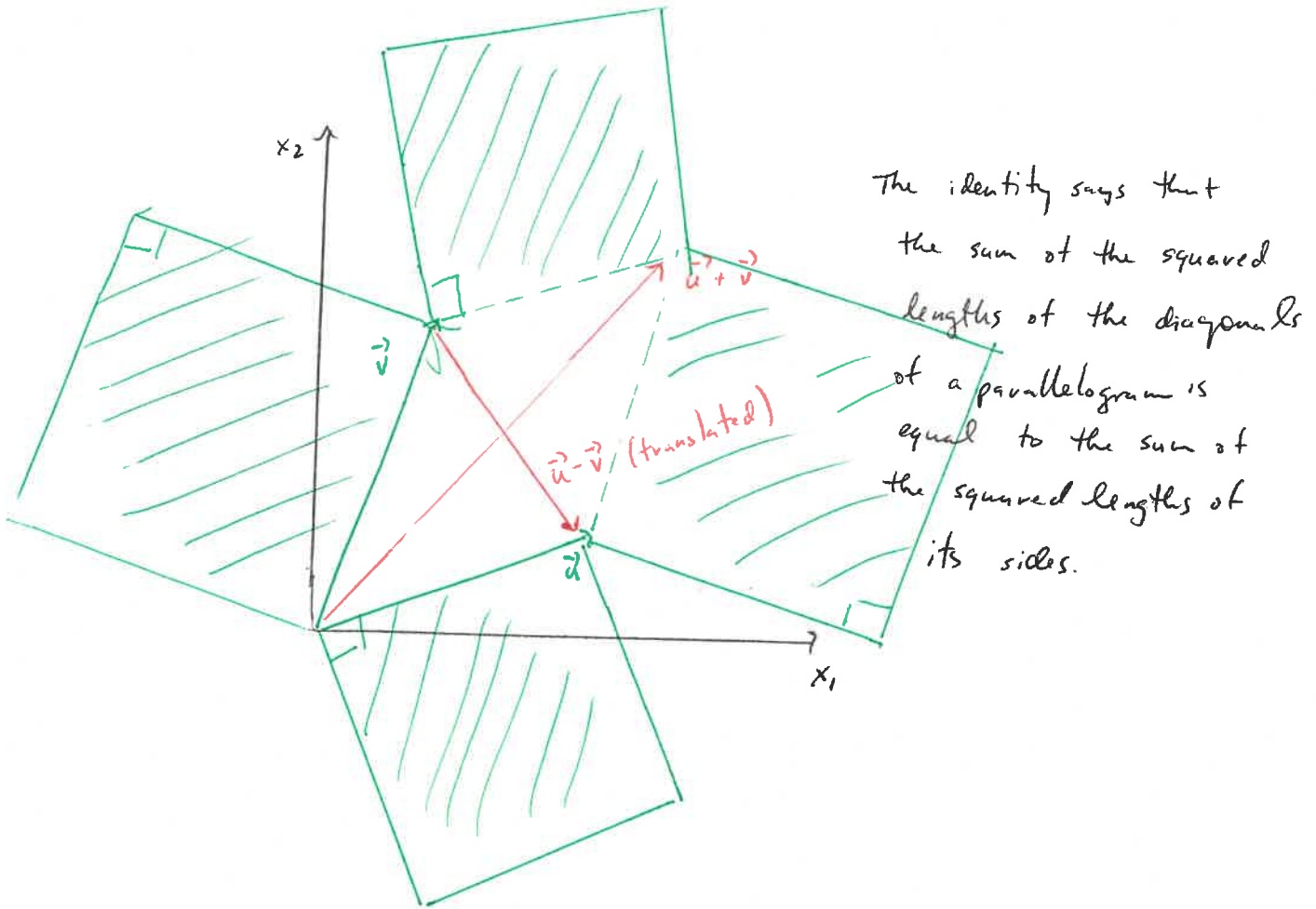


The identity says that the sum of the squared lengths of the diagonals of a parallelogram is equal to the sum of the squared lengths of its sides.

left side is the area of the two red squares.

- (4) [6 points] Let \mathbf{u} and \mathbf{v} be two vectors in \mathbb{R}^2 , each with positive coordinates. Draw a picture that illustrates vectors involved in the following identity. Then use this figure to explain what the identity is saying.

$$\|\mathbf{u} + \mathbf{v}\|^2 + \|\mathbf{u} - \mathbf{v}\|^2 = 2\|\mathbf{u}\|^2 + 2\|\mathbf{v}\|^2$$



right side is the area of the four shaded green squares.

The identity says these areas are equal.

* Can one build a 3-D model of this?

- (5) [5 points] Let $\mathbf{y} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$. Compute the distance from \mathbf{y} to the line through \mathbf{u} and the origin.

The Orthogonal Decomposition Theorem allows us to decompose \vec{y} into \hat{y} (its projection onto the line) and \vec{z} , a vector perpendicular to this line. The length of \vec{z} is the distance we seek.

$$\hat{y} = \underset{\text{proj}_{\text{Span}\{\vec{u}\}}}{\text{proj}} \vec{y} = \frac{\vec{y} \cdot \vec{u}}{\vec{u} \cdot \vec{u}} \vec{u} = \frac{6}{10} \begin{bmatrix} -1 \\ 3 \end{bmatrix} = \begin{bmatrix} -3/5 \\ 9/5 \end{bmatrix}.$$

$$\vec{z} = \vec{y} - \hat{y} = \begin{bmatrix} 3 \\ 3 \end{bmatrix} - \begin{bmatrix} -3/5 \\ 9/5 \end{bmatrix} = \begin{bmatrix} 18/5 \\ 6/5 \end{bmatrix}$$

$$\|\vec{z}\| = \sqrt{\left(\frac{18}{5}\right)^2 + \left(\frac{6}{5}\right)^2} = \sqrt{\frac{360}{25}} = \sqrt{\frac{36 \cdot 10}{25}} = \frac{6}{5} \sqrt{10}$$

- (6) (a) [10 points] Apply the Gram-Schmidt Process to the following set of vectors in \mathbb{R}^4 , $\mathbf{u}_1 = (1, 1, 1, 1)$, $\mathbf{u}_2 = (-1, 4, 4, -1)$, $\mathbf{u}_3 = (4, -2, 2, 0)$ which are a basis of some 3-dimensional subspace W . Call these new vectors $\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3$.

Applying the Gram-Schmidt Process:

$$\text{we let } \vec{a}_1 = \vec{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}.$$

$$\begin{aligned} \text{Then } \vec{a}_2 &= \vec{u}_2 - \text{proj}_{\text{Span}\{\vec{a}_1\}} \vec{u}_2 = \begin{bmatrix} -1 \\ 4 \\ 4 \\ -1 \end{bmatrix} - \frac{\vec{u}_2 \cdot \vec{a}_1}{\vec{a}_1 \cdot \vec{a}_1} \vec{a}_1 \\ &= \begin{bmatrix} -1 \\ 4 \\ 4 \\ -1 \end{bmatrix} - \frac{6}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -5/2 \\ 5/2 \\ 5/2 \\ -5/2 \end{bmatrix} \end{aligned}$$

Then

$$\begin{aligned} \vec{a}_3 &= \vec{u}_3 - \text{proj}_{\text{Span}\{\vec{a}_1, \vec{a}_2\}} \vec{u}_3 \\ &= \vec{u}_3 - \frac{\vec{u}_3 \cdot \vec{a}_1}{\vec{a}_1 \cdot \vec{a}_1} \vec{a}_1 - \frac{\vec{u}_3 \cdot \vec{a}_2}{\vec{a}_2 \cdot \vec{a}_2} \vec{a}_2 \\ &= \begin{bmatrix} 4 \\ -2 \\ 2 \\ 0 \end{bmatrix} - \frac{4}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{-10}{25} \begin{bmatrix} -5/2 \\ 5/2 \\ 5/2 \\ -5/2 \end{bmatrix} = \begin{bmatrix} 4 \\ -2 \\ 2 \\ 0 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 2 \\ 2 \\ -2 \end{bmatrix} = \begin{bmatrix} 2 \\ -2 \\ 2 \\ -2 \end{bmatrix}. \end{aligned}$$

So, we get the orthogonal basis $\{\vec{a}_1, \vec{a}_2, \vec{a}_3\} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -5/2 \\ 5/2 \\ 5/2 \\ -5/2 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 2 \\ -2 \end{bmatrix} \right\}$

- (b) [8 points] Let $A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3]$ and $\mathbf{b} = (0, 0, 0, 1)$. Find the least-squares solution of the equation $A\mathbf{x} = \mathbf{b}$.

Because the columns of A are orthogonal,
the orthogonal projection of $\vec{\mathbf{b}}$ onto $\text{Col } A$ is given

by

$$\begin{aligned} \hat{\mathbf{b}} &= \frac{\vec{\mathbf{b}} \cdot \vec{\mathbf{a}}_1}{\vec{\mathbf{a}}_1 \cdot \vec{\mathbf{a}}_1} \vec{\mathbf{a}}_1 + \frac{\vec{\mathbf{b}} \cdot \vec{\mathbf{a}}_2}{\vec{\mathbf{a}}_2 \cdot \vec{\mathbf{a}}_2} \vec{\mathbf{a}}_2 + \frac{\vec{\mathbf{b}} \cdot \vec{\mathbf{a}}_3}{\vec{\mathbf{a}}_3 \cdot \vec{\mathbf{a}}_3} \vec{\mathbf{a}}_3 \\ &= \frac{1}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \frac{-5/2}{25} \begin{bmatrix} -5/2 \\ 5/2 \\ 5/2 \\ -5/2 \end{bmatrix} + \frac{-2}{16} \begin{bmatrix} 2 \\ -2 \\ 2 \\ -2 \end{bmatrix} \\ &= \frac{1}{4} \vec{\mathbf{a}}_1 - \frac{1}{10} \vec{\mathbf{a}}_2 - \frac{1}{8} \vec{\mathbf{a}}_3. \end{aligned}$$

Thus, $\hat{\mathbf{x}} = \begin{bmatrix} 1/4 \\ -1/10 \\ -1/8 \end{bmatrix}$.