

Linear Algebra  
Exam 1  
Spring 2026

March 16, 2026

**Name:**

**Honor Code Statement:**

**Directions:** Complete all problems. Justify all answers/solutions; notice that some problems have writing limits. Outside sources are not permitted. There is a 90-minute time limit. The exam is proctored with permission of the Dean of the Faculty.

1. [20 points] Consider the following matrix below.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 1 & 1 & 1 \end{bmatrix}$$

- (a) Consider the homogeneous equation  $A\mathbf{x} = \mathbf{0}$ . Write the solution set to this equation in parametric vector form and describe the solution set geometrically.

(b) If possible, write the vector  $\mathbf{b} = \begin{bmatrix} -2 \\ -1 \\ -2 \end{bmatrix}$  as a linear combination of the columns of  $A$ .

(c) Is the mapping  $\mathbf{x} \mapsto A\mathbf{x}$  an onto mapping? Why or why not?

(d) Give two vectors in the domain of this mapping that map to the same vector in the codomain. Justify your answer.

2. [5 points] Use the figure below to set up a system of equations that models the general flow pattern of the network given. DO NOT solve this system.

3. [5 points] The following set of vectors form a set that is linearly independent. Indicate why, then give an additional vector to add to the set that would make the set of three linearly dependent. Justify your answer.

$$\mathbf{b}_1 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \mathbf{b}_2 = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}$$

4. [5 points] The following statement is false: “If a set in  $\mathbb{R}^3$  is linearly dependent, then the set contains more than 3 vectors.” Show that this is false by giving a counter-example.

5. [5 points] Show that  $T$  is a linear transformation by finding a matrix that implements the mapping.

$$T(x_1, x_2, x_3, x_4) = (x_1 + x_2, x_2 + x_3, x_3 + x_4, x_4)$$

6. [5 points] Determine whether a square matrix  $A$  with two identical rows is invertible.  
**Two sentence writing limit.**

7. [5 points] Suppose that  $A$  is a  $2 \times 2$  matrix such that  $AA = A^2 = I_2$ , that is,  $A$  is self-inverse. Show that the following block-partitioned matrix is also self-inverse.

$$M = \begin{bmatrix} A & 0 \\ I_2 & -A \end{bmatrix}$$

8. [5 points] **Fill-in-the-blank** Suppose that vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  span  $\mathbb{R}^3$ , and let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be a linear transformation such that  $T(\mathbf{v}_1) = T(\mathbf{v}_2) = T(\mathbf{v}_3) = \mathbf{0}$ . Then for any  $\mathbf{x}$  in  $\mathbb{R}^3$ , there are constants  $c_1, c_2, c_3$  such that  $\mathbf{x} = c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3$  because \_\_\_\_\_ . Then we can write

$$T(\mathbf{x}) = c_1T(\mathbf{v}_1) + c_2T(\mathbf{v}_2) + c_3T(\mathbf{v}_3)$$

since  $T$  preserves \_\_\_\_\_. Now since  $T(\mathbf{v}_1) = T(\mathbf{v}_2) = T(\mathbf{v}_3) = \mathbf{0}$ , we have that  $T(\mathbf{x})$  equals \_\_\_\_\_. In this way, we might name/describe  $T$  as the \_\_\_\_\_ transformation.